

# **CS499 - Fundamentals of Robotics**

## **Lab Assignment #5**

### **Fall 2010**

This lab will require you to use an Arduino to control a robot platform. The platform can either a “circular” robot, a “track” robot, or the irobot Create.

Your program should cause the robot to move forward, to turn left, and to turn right. For this exercise, this movement can be a fixed path that is programmed into the Arduino.