

Stand-by Redundancy

- ◆ When primary component fails, standby component is started up.
- ◆ Stand-by spares are cold spares => unpowered
- ◆ Switching equipment assumed failure free

Let X_i denote the lifetime of the i -th component from the time it is put into operation until its failure.

System lifetime:

$$X_{\text{sys}} = \sum_{i=1}^n X_i$$

Stand-by Redundancy

- ◆ MTTF $E(X) = \frac{n}{\lambda}$
 - gain is linear as a function of the number of components, unlike the case of parallel redundancy
 - added complexity of detection and switching mechanism

M-of-N System

Starting with N components, we need any M components operable for the system to be operable.

Example: TMR

$$R_{\text{TMR}}(t) = R_1(t)R_2(t)R_3(t) + R_1(t)R_2(t)(1 - R_3(t)) \\ + R_1(t)(1 - R_2(t))R_3(t) + (1 - R_1(t))R_2(t)R_3(t)$$

Where $R_i(t)$ is the reliability of the i-th component

if $R_i(t) = R_1(t) = R_2(t) = R_3(t) = R(t)$ then

$$R_{\text{TMR}}(t) = R^3(t) + 3R^2(t)(1 - R(t)) \\ = R^3(t) + 3R^2(t) - 3R^3(t) \\ = 3R^2(t) - 2R^3(t)$$

M-of-N System

The probability that exactly j components are not operating is

$$\binom{N}{j} Q^j(t) R^{N-j}(t) \quad \text{with} \quad \binom{N}{j} = \frac{N!}{j!(N-j)!}$$

then

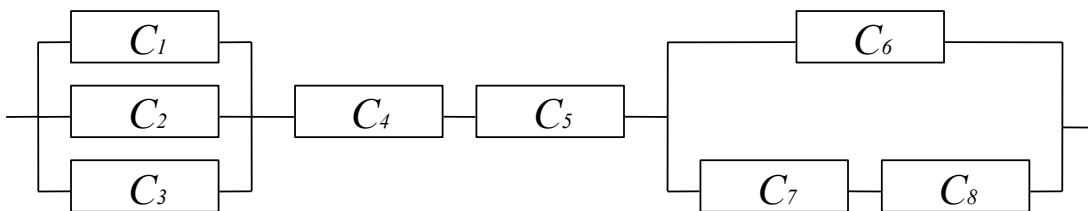
$$R_{\text{MofN}}(t) = \sum_{i=0}^{N-M} \binom{N}{i} Q^i(t) R^{N-i}(t)$$

Reliability Block Diagram

- ◆ Series Parallel Graph
 - a graph that is recursively composed of series and parallel structures.
 - therefore it can be “collapsed” by applying series and/or parallel reduction
 - Let C_i denote the condition that component i is operable
 - » 1 = up, 0 = down
 - Let S denote the condition that the system is operable
 - » 1 = up, 0 = down
 - S is a logic function of C 's

Reliability Block Diagram

- Example:



$$S = (C_1 + C_2 + C_3)(C_4 C_5)(C_6 + C_7 C_8)$$

+ => parallel (1 of N)

. => series (N of N)

K of N system

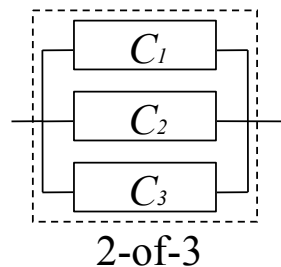
- ◆ Example 2-of-3 system

$$S = (C_1 C_2 + C_1 C_3 + C_2 C_3)$$

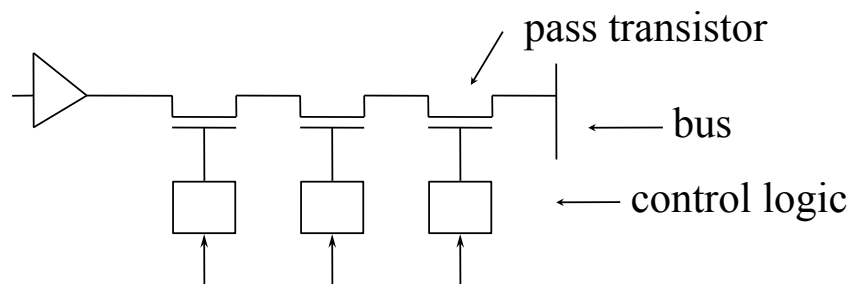
may abbreviate

$$S = \frac{2}{3} (C_1 C_2 C_3)$$

draw as parallel



Example: Bus-Guardian



- assume λ for transistor & logic $\lambda = 2 \times 10^{-5}$
- 50/50 split: fail-on/fail-off

Two failure states for system

- Q_A = failed active (babbling) with λ_A
- Q_P = failed passive with λ_P

Example: Bus-Guardian

$$\lambda = 2 \times 10^{-5}$$

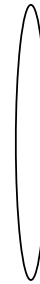
$$\lambda_A = 1 \times 10^{-5}$$

$$\lambda_P = 1 \times 10^{-5}$$

$$MTTF = \frac{1}{\lambda} = 5 \times 10^4$$

$$MTTF_A = \frac{1}{\lambda_A} = 10^5$$

$$MTTF_P = \frac{1}{\lambda_P} = 10^5$$

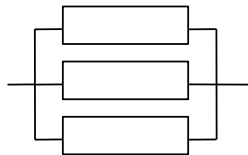


for each
stage

Example: Bus-Guardian

◆ Active Failure

- if any one bus guardian is correct then no babble possible
- thus we use 1-of-N parallel system model



$$Q(t) = \prod_{i=1}^3 Q_i(t)$$

with $Q_i(t) = 1 - e^{-\lambda_A t}$

Example: Bus-Guardian

- Solution - Parallel
 - » if any one bus guardian is correct then no babble possible
 - » 1-of-N parallel system model

$$\begin{aligned}Q(t) &= (1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t}) \\ &= 1 - 3e^{-\lambda_A t} + 3e^{-2\lambda_A t} - e^{-3\lambda_A t}\end{aligned}$$

e.g. with $\lambda_A = 10^{-5} / h$ and $t = 1000h$

$$\lambda_A t = 0.01$$

Example: Bus-Guardian

compute: $Q(t) = 1 - 3e^{-\lambda_A t} + 3e^{-2\lambda_A t} - e^{-3\lambda_A t}$

$$\begin{aligned}Q(1000h) &= 1 - 3(0.9900498) + 3(0.9801987) - (0.9704455) \\ &= 1.2 \times 10^{-6}\end{aligned}$$

compute:

$$\begin{aligned}Q(t) &= (1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t}) \\ &= (1 - e^{-\lambda_A t})^3\end{aligned}$$

$$Q(1000h) = 0.9851243 \times 10^{-6}$$

in general: danger of cancellation
=> catastrophic results,
=> legal issues (even though one
should realize what the fail rates really
mean)

Example: Bus-Guardian

$$\begin{aligned}
 \text{MTTF}_A &= \int_0^{\infty} R(t) dt = \int_0^{\infty} 1 - Q(t) dt \\
 &= \int_0^{\infty} (3e^{-\lambda_A t} - 3e^{-2\lambda_A t} + e^{-3\lambda_A t}) dt \\
 &= \left[-\frac{3}{\lambda_A} e^{-\lambda_A t} + \frac{3}{2\lambda_A} e^{-2\lambda_A t} - \frac{1}{3\lambda_A} e^{-3\lambda_A t} \right]_0^{\infty}
 \end{aligned}$$

simplification:

$$e^{-\lambda_A t} = 0 \text{ as } t \rightarrow \infty$$

$$e^{-\lambda_A t} = 1 \text{ with } t = 0$$

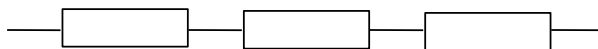
$$\begin{aligned}
 \text{MTTF}_A &= \frac{3}{\lambda_A} - \frac{3}{2\lambda_A} + \frac{1}{3\lambda_A} \\
 &= \left(3 - \frac{3}{2} + \frac{1}{3}\right) \times 10^5 \\
 &= 1.83 \times 10^5 \text{ h}
 \end{aligned}$$

3 drivers result in approx. MTTF of twice and not three times that of single driver

Example: Bus-Guardian

◆ Passive Failure

- any one of N bus guardians can take out subsystem
- thus we use series system model



$$\begin{aligned}
 R(t) &= \prod_{i=1}^3 R_i(t) \\
 &= e^{-\sum_{i=1}^3 \lambda_i t} \\
 &= e^{-3\lambda t}
 \end{aligned}$$

Given $\lambda = 1 \times 10^{-5}$ $t = 1000\text{h}$

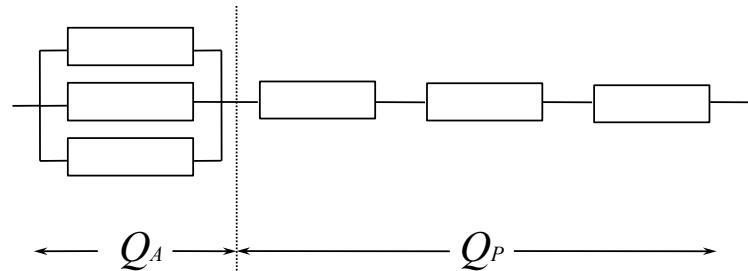
$$R(t) = e^{-3\lambda t} = 0.9704455$$

$$\Rightarrow \text{MTTF} = \frac{1}{\lambda_{\text{sys}}} = 33333\text{h}$$

Example: Bus-Guardian

◆ summary

- active failure \Rightarrow parallel $\Rightarrow Q_A$
- passive failure \Rightarrow series $\Rightarrow Q_P$
- whole system fails if either mode occurs \Rightarrow series



Example: Bus-Guardian

◆ summary

	Simplex	Triplex
$MTTF_A$	$1 \times 10^5 h$	$1.8 \times 10^5 h$
$MTTF_P$	$1 \times 10^5 h$	$0.33 \times 10^5 h$
$MTTF$	$0.5 \times 10^5 h$	$0.28 \times 10^5 h$

$$MTTF = \frac{MTTF_A \times MTTF_P}{MTTF_A + MTTF_P}$$

What is the unreliability Q_A ?

- ◆ Two approaches to compute $Q(t)$ at 1000h

$$\begin{aligned} 1) \quad Q(t) &= (1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t})(1 - e^{-\lambda_A t}) \\ &= 1 - 3e^{-\lambda_A t} + 3e^{-2\lambda_A t} - e^{-3\lambda_A t} \end{aligned}$$

$$2) \quad MTTF_A = 1.8333 \times 10^5$$

using $MTTF = \frac{1}{\lambda}$ we compute λ and use

$$Q(t) = (1 - e^{-\lambda t})$$

Now we compute $Q(1000)$ and ...

