

Survivability Applications

- This sequence is based on the paper:
 - Li Tan, and Axel W. Krings, “An Adaptive N-variant Software Architecture for Multi-Core Platforms: Models and Performance Analysis”, The 11th International Conference on Computational Science and Its Applications (ICCSA 2011), in Lecture Notes on Computer Science (LNCS), Springer Verlag, 2011, (16 pages)
 - Other material is from the references of that publication
 - The focus here is on system architectures for survivability and formal analysis tools.

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Multi-core Systems

- **They are here and they will grow!**
- Assumptions about the future of multi-core
 - number of cores is increasing
 - most applications still have limited means of using multi-threading
 - degree of parallelism is bound by the largest anti-chain of the execution graph
 - implications on speedup

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Reliability and Redundancy

- Redundancy has greatly benefitted reliability
- In the past: homogeneous redundancy
- New focus on heterogeneous redundancy
 - avoidance of common mode faults

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Common Mode Faults

- If a SW/HW component fails under a certain input, then it does not matter how many identical components one uses for redundancy => **they all fail**
- Dissimilarity as an approach toward independence of faults
- Two main approaches
 - N-version software
 - N-variant software

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N-version Software

- N-version programming (late 70s)
 - software is derived by multiple teams from the same specification in isolation
 - expectation: common mode fault is reduced or eliminated
 - different results by different versions indicate fault
 - limitations
 - how dissimilar are implementations?
 - is there true independence of development?
 - how does one measure the “degree of dissimilarity”?

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N-variant Software

- Inspired by N-version software
- Different variants are generated in a more “automated” fashion
- Expectation is that a fault affecting on variant will not affect another in an identical way
- Again, differences detected by different variants indicate fault

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Resilient Multi-core systems

- Utilize idle resources to increase resilience
- Specifically

Utilize idle cores for resilience mechanisms

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Related work

- Towards Byzantine Fault Tolerance in Many-core Computing Platforms, Casey M. Jeffery and Renato J. O. Figueiredo, 13th IEEE International Symposium on Pacific Rim Dependable Computing, 2007
- Focus on transient faults

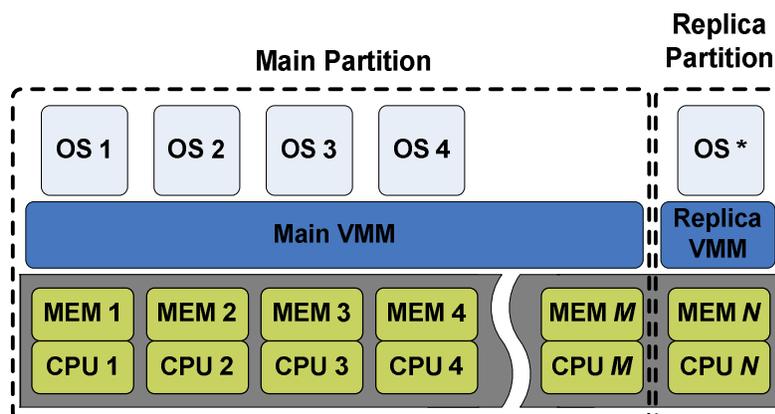


Figure 1. Many-core model with replica partition.

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Related work [Cox2006]

- N-Variant Systems A Secretless Framework for Security through Diversity, B. Cox, et. al., USENIX, 2006
 - A set of automatically diversified variants execute on same inputs
 - Difference in referencing memory is observed
 - Identifies execution of injected code
 - Check out section 3. **Model** of their paper

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Related work [Cox2006]

- Example of two variants using disjoint memory space. Any absolute memory access will be invalid in one the variants

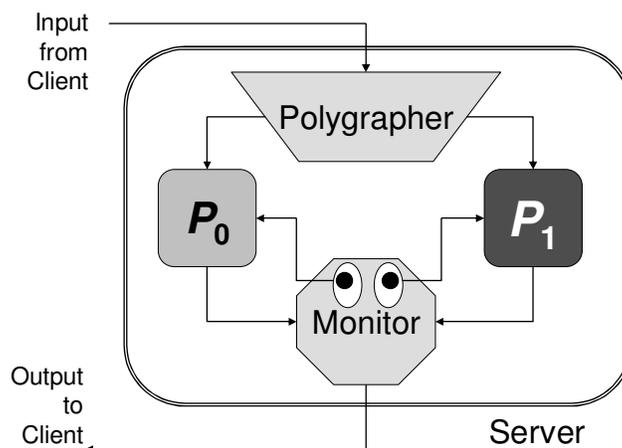


Figure 1. N-Variant System Framework.

[Nguyen-Tuong 2008]

- Security through redundant data diversity
 - Anh Nguyen-Tuong, David Evans, John C. Knight, Benjamin Cox, Jack W. Davidson
 - 38th IEEE/IFPF International Conference on Dependable Systems and Networks, Dependable Computing and Communications Symposium. Anchorage, June 2008.

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[Nguyen-Tuong 2008]

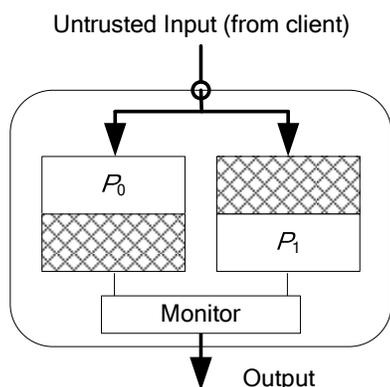


Figure 1. Two-variant address partitioning.

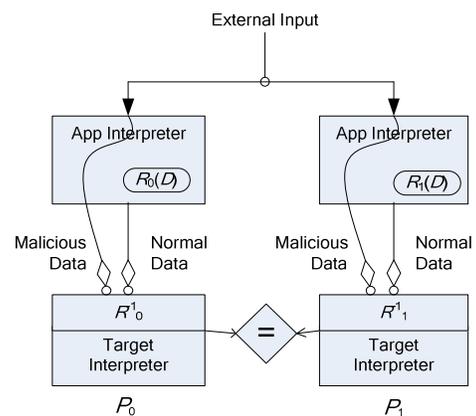


Figure 2. N-Variant Systems with Data Diversity.

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Related work [Salamat2008]

- B. Salamat, et. al. 2008
 - Multi-Variant Program Execution: Using Multi-Core Systems to Defuse Buffer-Overflow Vulnerabilities
 - International Conference on Complex, Intelligent and Software Intensive Systems
 - Variants use different direction in memory allocation
 - Buffer overflow “crashes” into different neighboring memory

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Related work [Salamat2008]

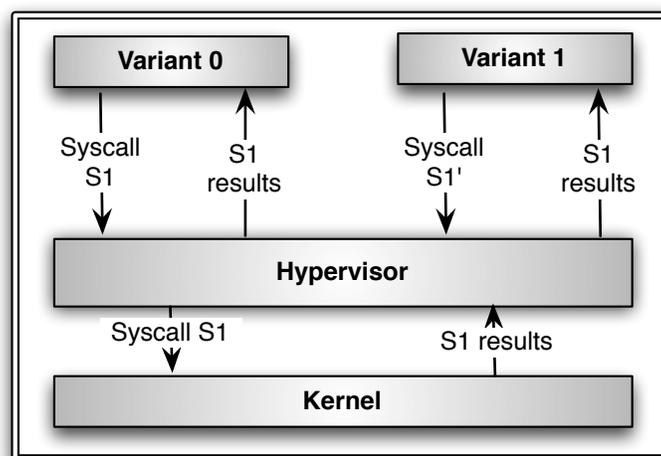


Figure 1. System calls that change the global state are executed by the monitor and the results are communicated to all instances.

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General Scheme

- Execution of multiple versions masks or detects faults
- Overhead
 - N-folding amount of work
 - Redundancy management
- What can be absorbed?

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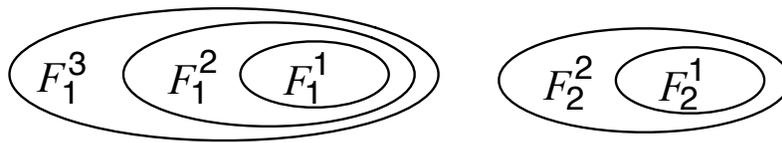
Two Step Approach

- Specification Model
- Layered adaptive architecture

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Specification Model

- Adaptive Functional Capability Model (AFCM)
 - System comprised of functionalities $F_1 \cdots F_m$
 - core operations that are mission critical
 - non-critical, but value-added operations



$$F_1^1 \preceq F_1^2 \preceq F_1^3$$

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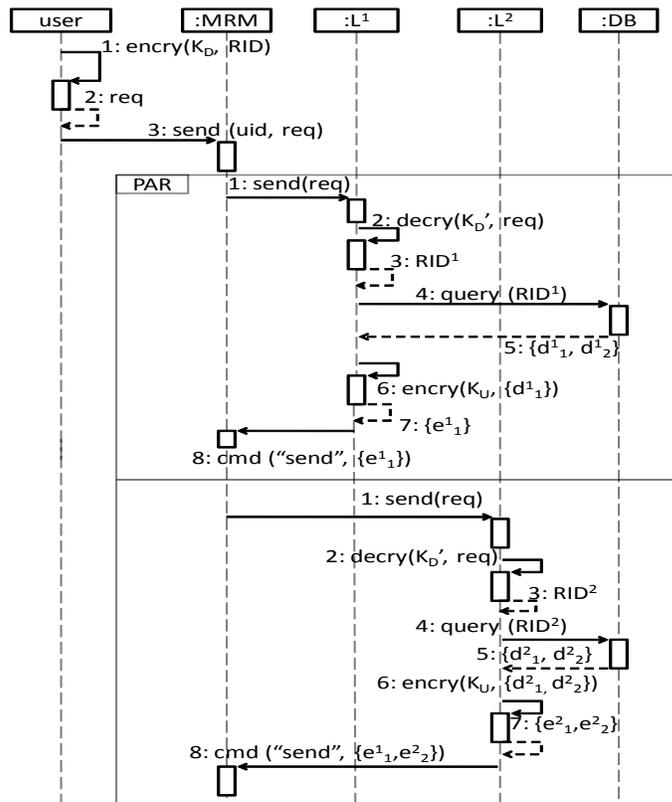
Example: Multi-level Secured Record Keeping

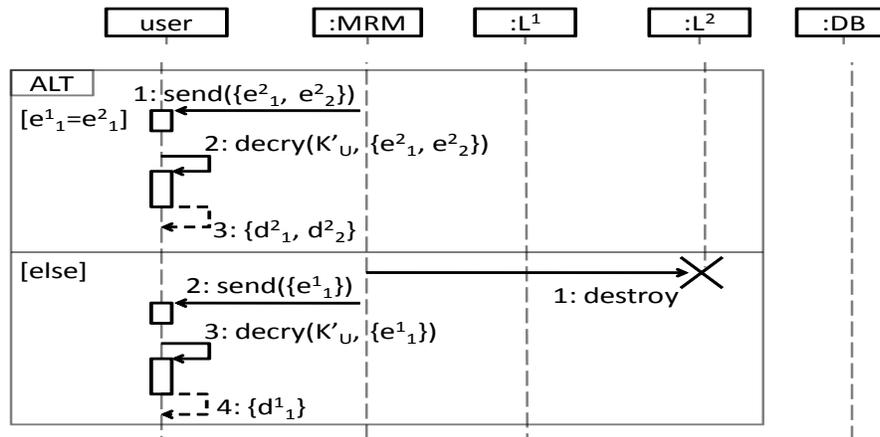
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Example

- Secured database system D
 - each record in D contains two sets of data, i.e., $d = \{d_1, d_2\}$
 - d_1 contains mission critical data
 - d_2 non-mission critical, but value-added data

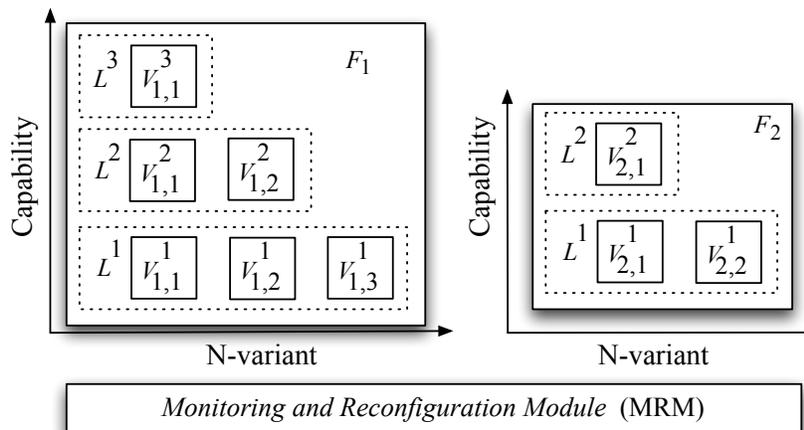
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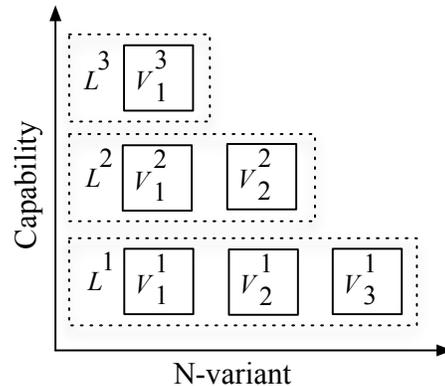
Layered N-variant Architecture

- Multiple functionalities:
 - System is a collection of functionalities



Adaptability and Reconfiguration

- Layers have two purposes
 - lower layer monitors higher layer
 - layers are basis for reconfiguration
 - disagreement results in
 - scaling back to lower layer
 - graceful degradation



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Special Cases

- Limitation of current research
 - all functionalities are defined on same layer
- Salamat, et. al. 2008
 - use two variants at the same layer, i.e., layer L_1
 V_1^1 and V_2^1
 - the two variants focus on memory referencing

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Special Cases

- Cox, et. al. 2006
 - use variants at the same layer, i.e., layer L_1
 - the variants focus on memory referencing

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Matching expectations

- Specify a suitable system
 - get an idea with GSPN model (Gen. Stochastic Petri Nets)
 - see if/how goal can be met
 - see if the overhead realistic
- Implementation
 - probabilistic automaton-based model
 - closer to real behavior
 - starting point towards implementation

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Petri Nets

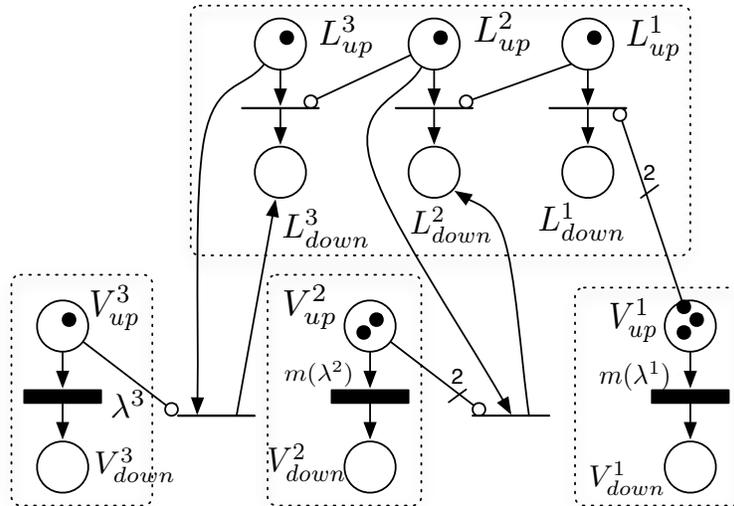
- From Markov Chains to Petri Nets
 - discussion on Markov Chains
 - discussion on Petri Nets
 - you will not be an expert based on this discussion, but you should understand the general ideas, the strength and mathematical/computational limitations.

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extra page for notes

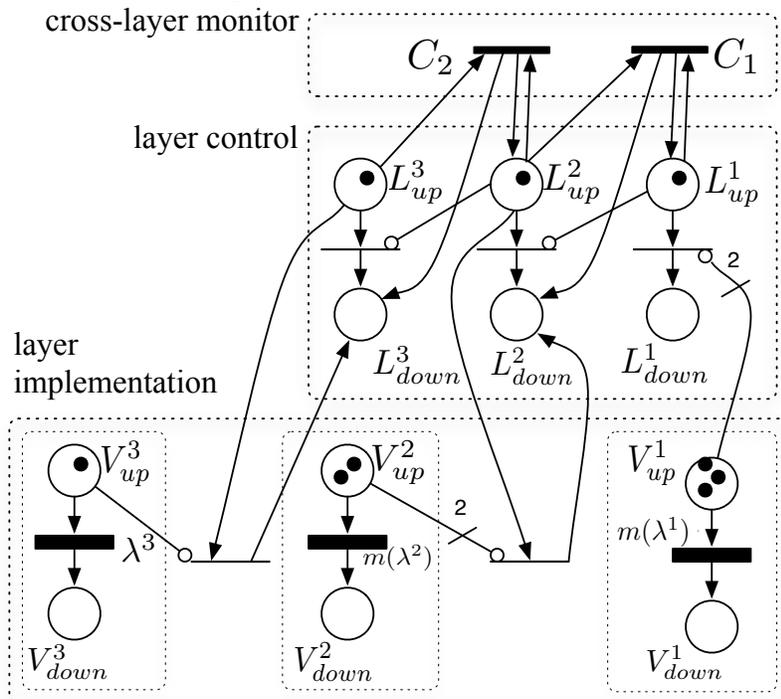
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Reliability and Resilience



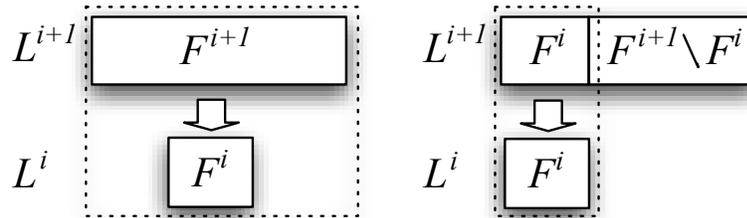
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Reliability and Resilience



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Cross-layer monitoring scope

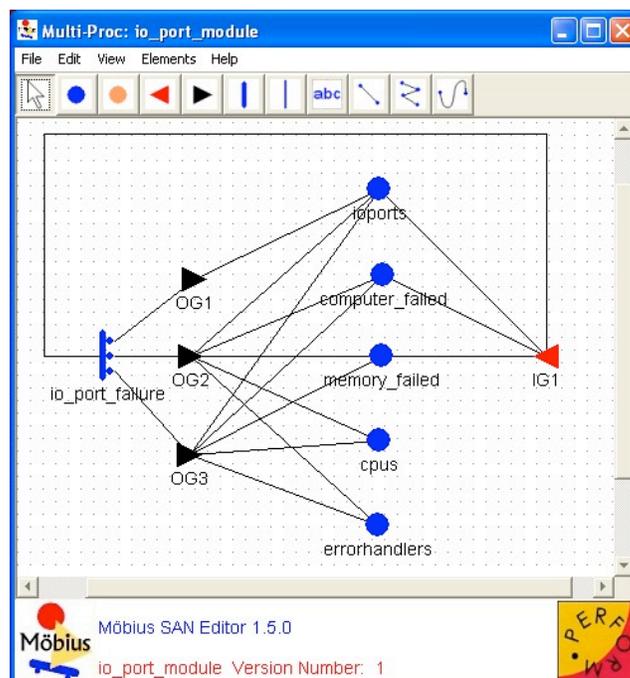


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Stochastic Activity Networks

- Example:
Möbius

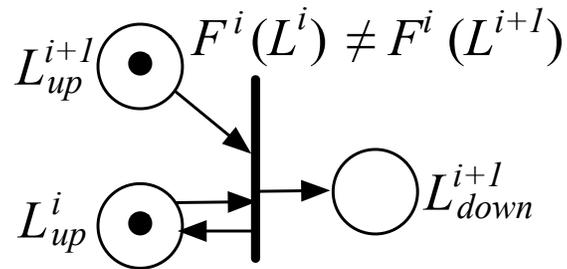
check out
www.mobius.illinois.edu



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SAN for cross-layer monitoring

- Note the difference between GSPN and SAN (Stochastic Activity Network)



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Stochastic Models

- Evaluation of performance of architecture
 - model stochastic behavior using probabilistic models
 - use probabilistic model checking
- Metrics of interest
 - service availability
 - information security

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Probabilistic Automata

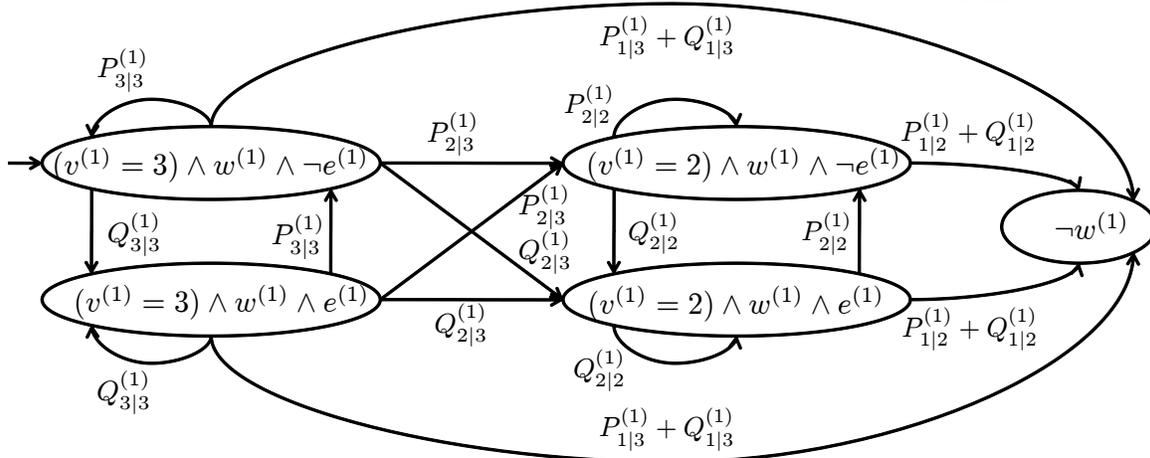
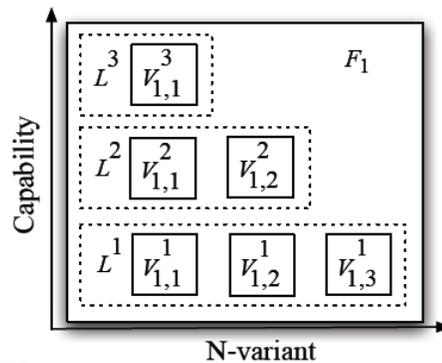
N-tuple $\langle Q, \Theta, \delta, Q_0, F, P_\delta, P_0 \rangle$

1. Q is a set of states,
2. Θ is a set of input symbols,
3. $\delta \subseteq Q \times \Theta \times Q$ is a set of transitions,
4. $Q_0 \subseteq Q$ is a set of start states,
5. $F \subseteq Q$ is a set of accepting states,
6. $P_\delta : \delta \rightarrow (0, 1]$ assigns each transition a probability, and
7. $P_0 : Q_0 \rightarrow (0, 1]$ assigns each start state a probability.

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Probabilistic automaton:
Example 1

L^1 of F_1



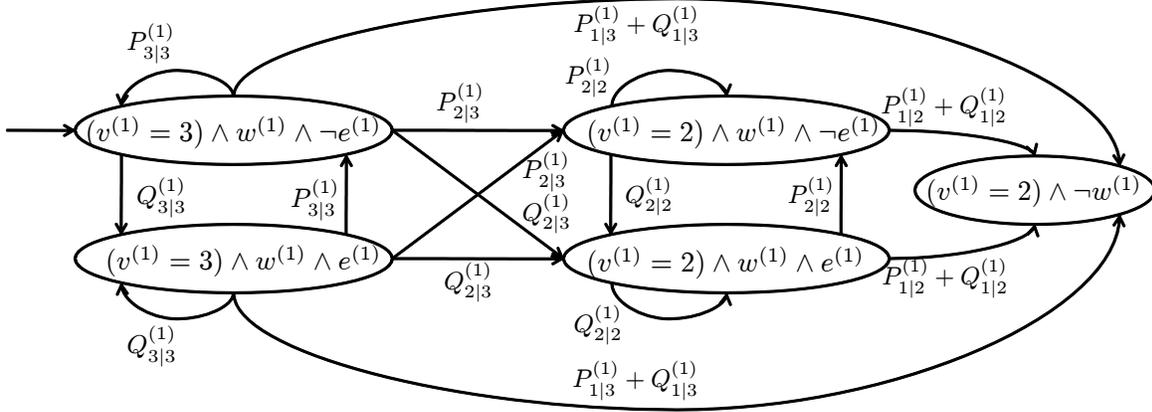
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$P_{k|n}$ is the probability that,

1. The maximal number of n variants producing the same result is k , and;
2. The result is *correct*.

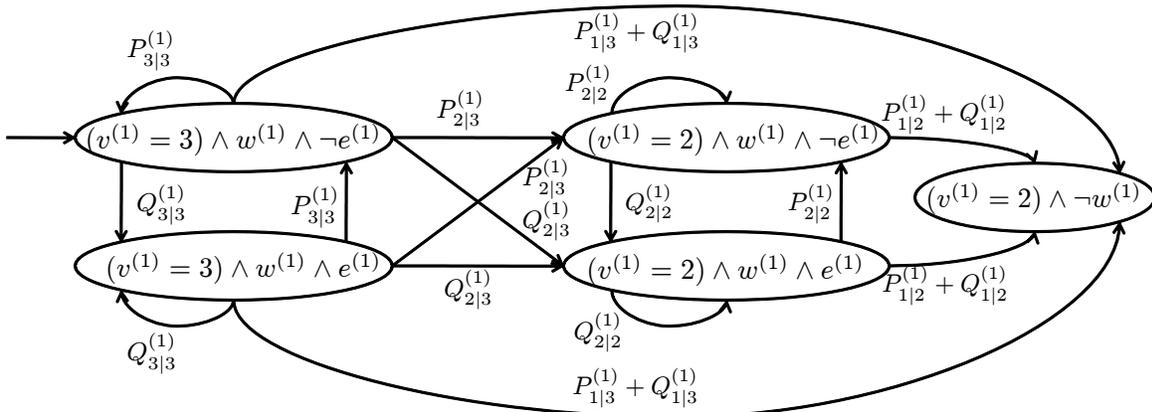
$Q_{k|n}$ is the probability that,

1. The maximal number of n variants producing the same result is k , and;
2. The result is *incorrect*.



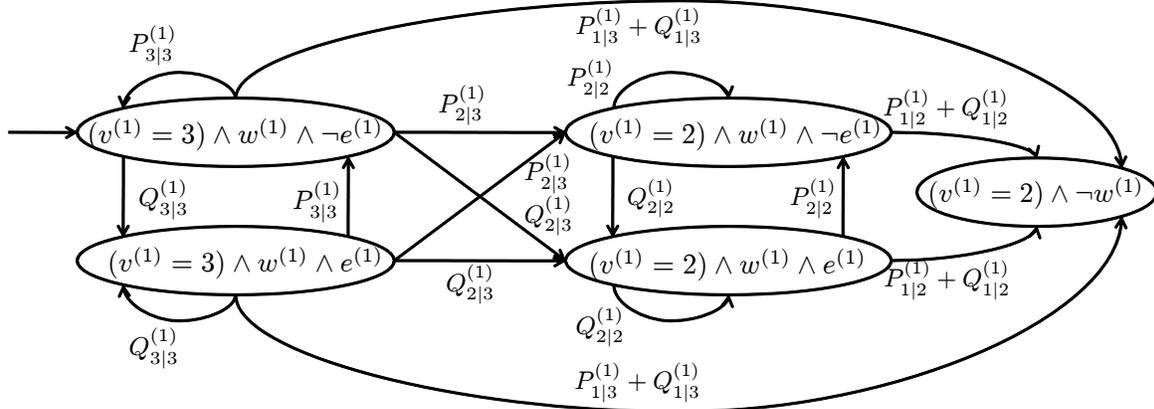
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v , the number of working variants. The built-in voting mechanism decides the status of variants by simple majority. For example, if at the start of a clock cycle all 3 variants are working and during the cycle only 2 of 3 variants produce the same result, then the voting mechanism will mark these 2 variants as working, and the other one as *not* working;



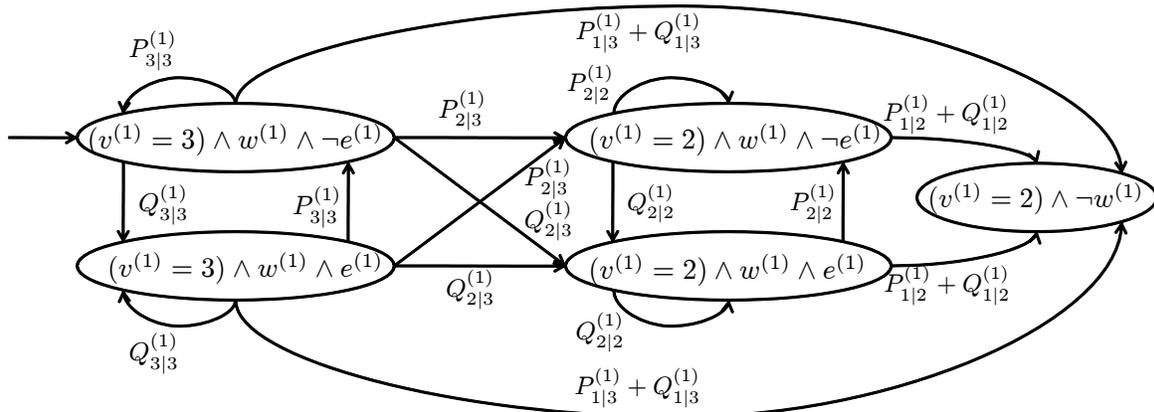
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w , the status of a layer. Initially all layers are working. If at one point the voting mechanism cannot decide which variant it can trust, for instance, in case that all 2 working variants report different value, it simply marks the layer as *not* working;



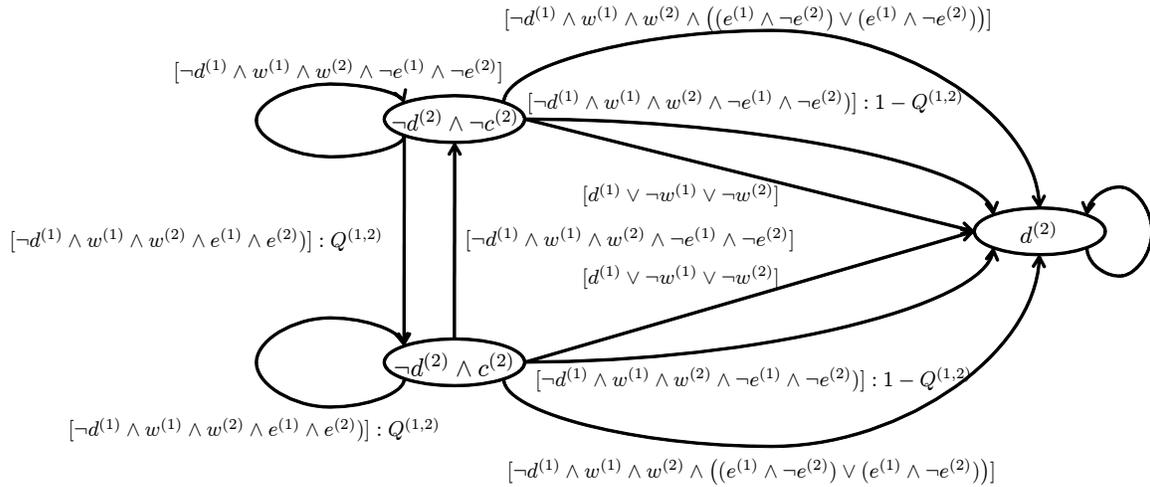
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e , the error flag. $e = true$ indicates that an erroneous output is produced by the layer. This could happen when, for example, all the working variants produce the exactly same erroneous output, although this is a very unlikely scenario especially when we apply N-variant technique. We will discuss this in more details later.



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Monitoring and Reconfiguration Sub-Module in layer 2 (MRSM2)



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Computational Experiments

■ Analysis used:

- Symbolic Hierarchical Automated Reliability/Performance Evaluator (SHARPE) to analyze GSPNs
- Probabilistic model checker PRISM to analyze the probabilistic automaton-based model

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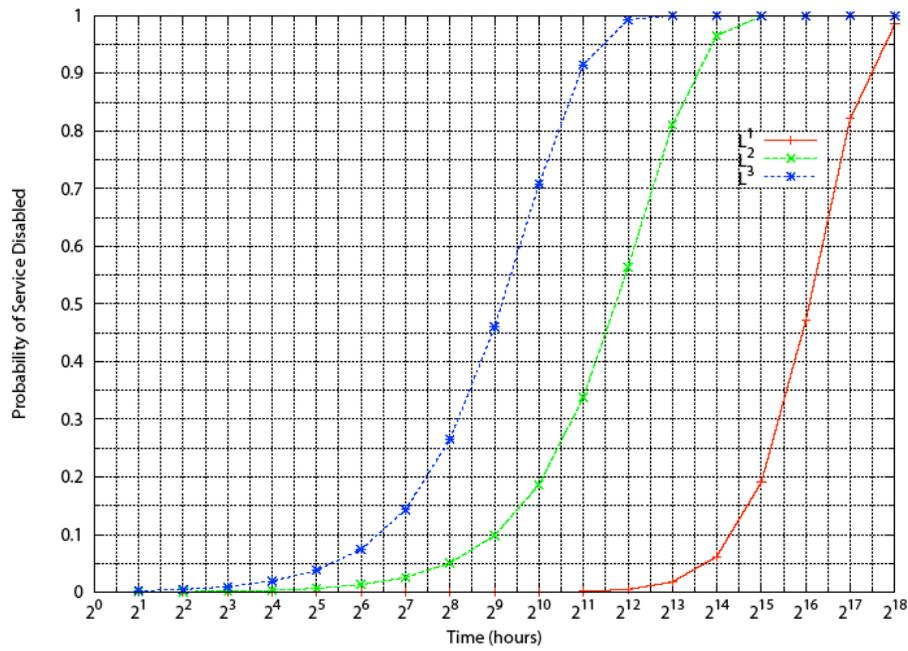


Figure 8. Probability of services being disabled for the GSPN model.

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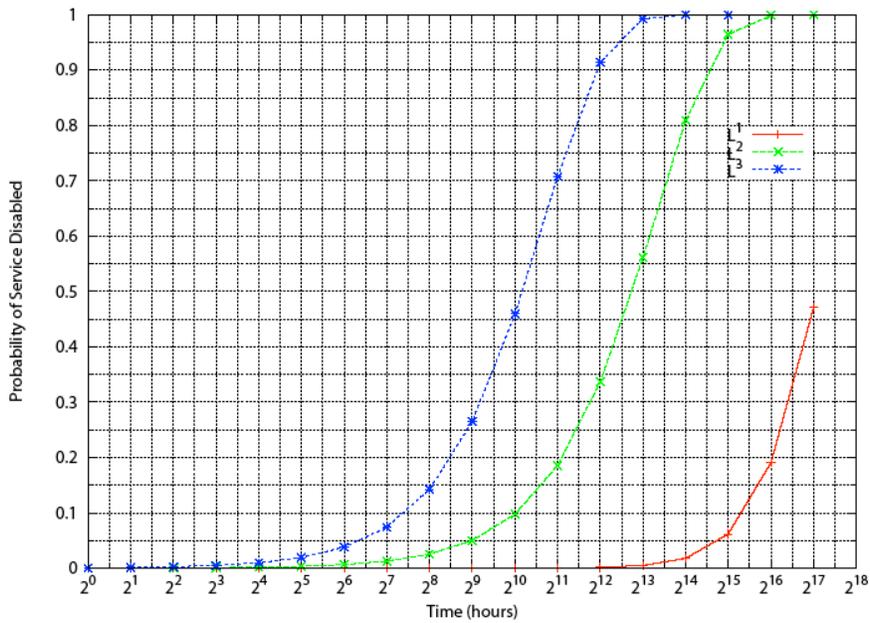
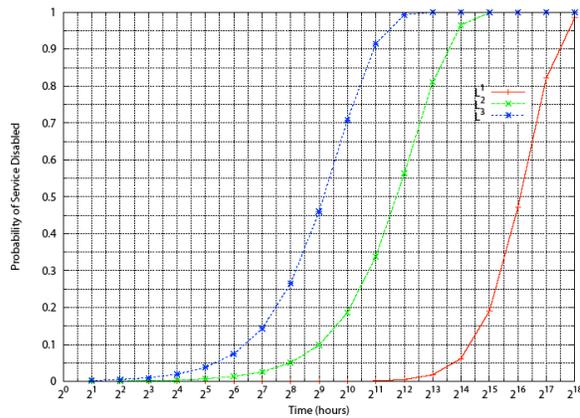
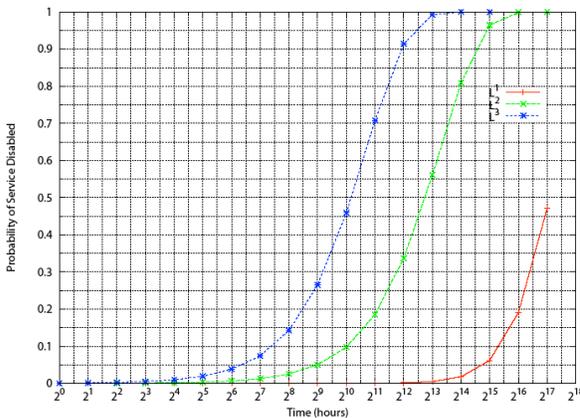


Figure 9. Probability of services being disabled for the probabilistic automaton-based model.

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GSPN model



Probability Automaton-based model

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Conclusions

- 🕒 Hierarchical Formal Model was introduced
 - 🕒 Adaptive Functional Capability Model (AFCM)
 - 🕒 Multi-layer architecture
 - 🕒 Adaptation capabilities
 - 🕒 Reconfiguration capabilities
 - 🕒 Use Petri Net to deal with design specification experimentation
 - 🕒 Use model checking to go from design to implementation