

Using Semaphores

- It is difficult to use semaphores
 - see example in Fig 5.9
 - semaphores may be scattered throughout the program
 - difficult to assess overall effect
- Monitors provide similar functionality
 - but are easier to control
 - implemented in languages like Concurrent Pascal, Pascal-Plus, Modula-2 & 3, and Java

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Monitors

- A Monitor is a software module
- Chief characteristics
 - Local data variables are accessible only by the monitor
 - Process enters monitor by invoking one of its procedures
 - Only one process may be executing in the monitor at a time

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Monitors

- Provides mutual exclusion facility
- Shared data structure can be protected by placing it into a monitor
- If the data in a monitor represents some resource, then mutual exclusion is guaranteed for that resource

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Monitors

- Synchronization support is needed
 - implemented using special data types called *condition variables*
 - these variables are affected by two functions
 - `cwait(c)`
 - suspend calling process on condition `c`
 - now monitor can be used by other process
 - `csignal(c)`
 - resume blocked process after `cwait` on same condition `c`

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Monitors

- So what is the difference between the use of cwait and csignal in monitors and the wait and signal of semaphores?
 - Hint: remember what got us in trouble when using semaphores

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Monitors

- Monitor wait and signal operations are different from their counterparts in semaphores
 - If a process in a monitor signals and corresponding queue is empty then signal is lost

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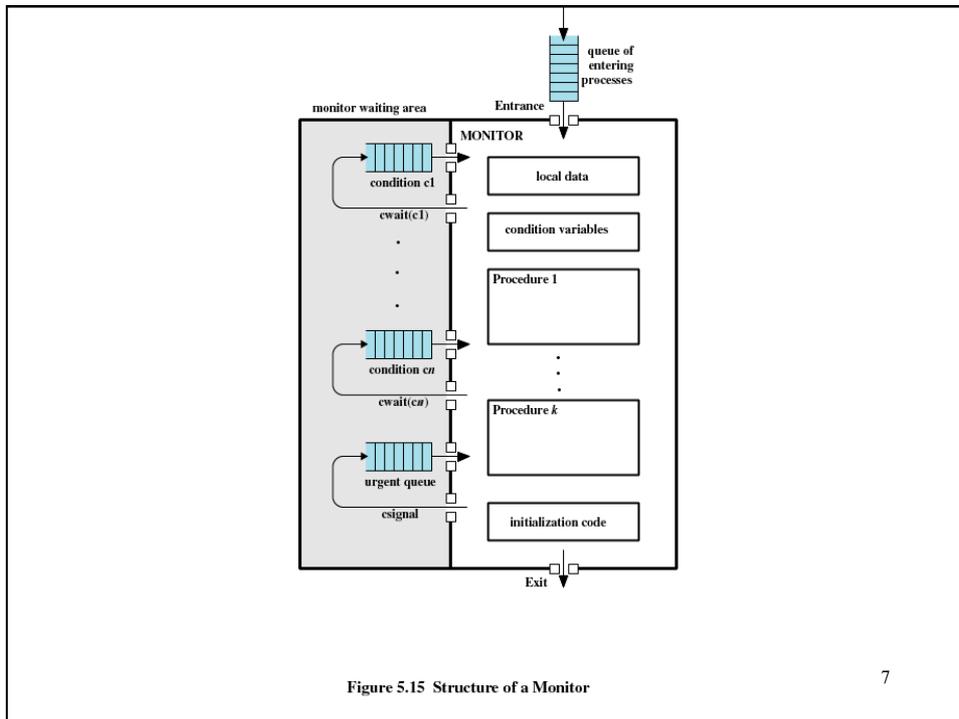


Figure 5.15 Structure of a Monitor

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```

/* program producerconsumer */
monitor boundedbuffer;
char buffer [N];                               /* space for N items */
int nextin, nextout;                            /* buffer pointers */
int count;                                     /* number of items in buffer */
cond notfull, notempty;                       /* condition variables for synchronization */

void append (char x)
{
    if (count == N)
        cwait(notfull);                       /* buffer is full; avoid overflow */
    buffer[nextin] = x;
    nextin = (nextin + 1) % N;
    count++;
    /* one more item in buffer */
    csignal(notempty);                        /* resume any waiting consumer */
}

void take (char x)
{
    if (count == 0)
        cwait(notempty);                     /* buffer is empty; avoid underflow */
    x = buffer[nextout];
    nextout = (nextout + 1) % N;
    count--;
    /* one fewer item in buffer */
    csignal(notfull);                         /* resume any waiting producer */
}

{
    nextin = 0; nextout = 0; count = 0;        /* monitor body */
}
/* buffer initially empty */

```

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```
void producer()
char x;
{
    while (true)
    {
        produce(x);
        append(x);
    }
}
void consumer()
{
    char x;
    while (true)
    {
        take(x);
        consume(x);
    }
}
void main()
{
    parbegin (producer, consumer);
}
```

Figure 5.16 A Solution to the Bounded-Buffer Producer/Consumer Problem Using a Monitor

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Message Passing

- Interaction between processes
 - synchronization
 - communication
- One solution to this is message passing
 - works in tightly and loosely coupled systems

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Message Passing

- Enforce mutual exclusion
- Exchange information

send (destination, message)

receive (source, message)

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Synchronization

- Sender and receiver may or may not be blocking (waiting for message)
- Blocking send, blocking receive
 - Both sender and receiver are blocked until message is delivered
 - This is called a *rendezvous*

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Synchronization

- Nonblocking send, blocking receive
 - Sender continues on
 - Receiver is blocked until the requested message arrives
- Nonblocking send, nonblocking receive
 - Neither party is required to wait

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Addressing

- Direct addressing
 - Send primitive includes a specific identifier of the destination process
 - Receive primitive could know ahead of time which process a message is expecting
 - Receive primitive could use source parameter to return a value when the receive operation has been performed

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Addressing

- Indirect addressing
 - Messages are sent to a shared data structure consisting of queues
 - Queues are called *mailboxes*
 - One process sends a message to the mailbox and the other process picks up the message from the mailbox
 - relationship between sender & receiver
 - 1-to-1, many-to-1, 1-to-many, many-to-many

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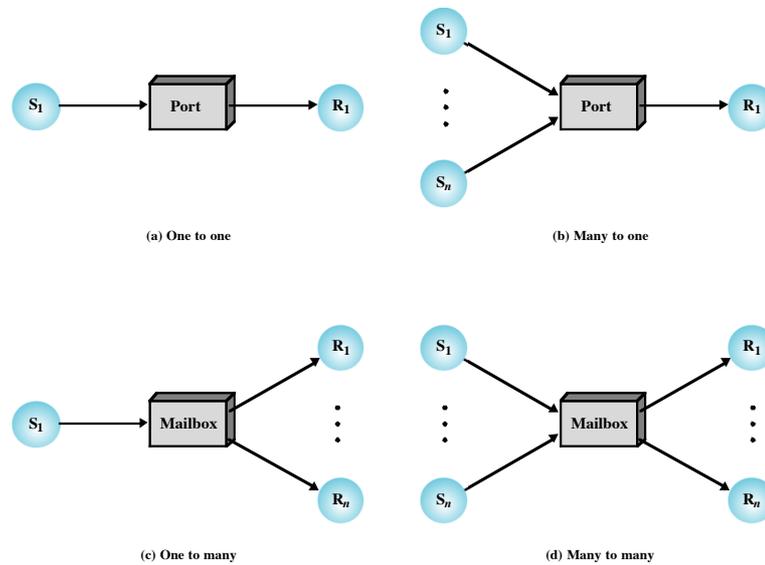


Figure 5.18 Indirect Process Communication

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Message Format

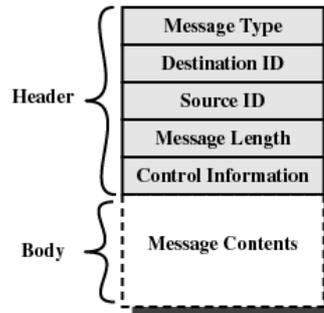


Figure 5.19 General Message Format

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Assumptions:
blocking receive
non-blocking send

```
/* program mutualexclusion */
const int n = /* number of processes */;
void P(int i)
{
    message msg;
    while (true)
    {
        receive (mutex, msg);
        /* critical section */;
        send (mutex, msg);
        /* remainder */;
    }
}
void main()
{
    create_mailbox (mutex);
    send (mutex, null);
    parbegin (P(1), P(2), . . . , P(n));
}
What happens if the
send is omitted?
```

Figure 5.20 Mutual Exclusion Using Messages

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```

const int
  capacity = /* buffering capacity */ ;
  null = /* empty message */ ;
int i;
void producer()
{
  message pmsg;
  while (true)
  {
    receive (mayproduce, pmsg);
    pmsg = produce();
    send (mayconsume, pmsg);
  }
}
void consumer()
{
  message cmsg;
  while (true)
  {
    receive (mayconsume, cmsg);
    consume (cmsg);
    send (mayproduce, null);
  }
}
void main()
{
  create_mailbox (mayproduce);
  create_mailbox (mayconsume);
  for (int i = 1; i <= capacity; i++)
    send (mayproduce, null);
  parbegin (producer, consumer);
}

```

What does the for loop do?

Figure 5.21 A Solution to the Bounded-Buffer Producer/Consumer Problem Using Messages

Readers/Writers Problem

- Different variations on the theme, e.g.,
 - dedicated readers and dedicated writers
 - they all can read and write
- Here we look at the “dedicated” case
 - Any number of readers may simultaneously read the file
 - Only one writer at a time may write to the file
 - If a writer is writing to the file, no reader may read it

```

/* program readersandwriters */
int readcount;
semaphore x = 1, wsem = 1;
void reader()
{
    while (true)
    {
        semWait (x);
        readcount++;
        if (readcount == 1)
            semWait (wsem);
        semSignal (x);
        READUNIT ();
        semWait (x);
        readcount--;
        if (readcount == 0)
            semSignal (wsem);
        semSignal (x);
    }
}
void writer()
{
    while (true)
    {
        semWait (wsem);
        WRITEUNIT ();
        semSignal (wsem);
    }
}
void main()
{
    readcount = 0;
    parbegin (reader, writer);
}

```

x: controls updating readcount
wsem: controls writing

Figure 5.22 A Solution to the Readers/Writers Problem Using Semaphores: Readers Have Priority

```

/*program readersandwriters*/
int readcount, writecount;
semaphore x = 1, y = 1, z = 1, wsem = 1, rsem = 1;
void reader()
{
    while (true)
    {
        semWait (z);
        semWait (rsem);
        semWait (x);
        readcount++;
        if (readcount == 1)
            semWait (wsem);
        semSignal (x);
        semSignal (rsem);
        semSignal (z);
        READUNIT ();
        semWait (x);
        readcount--;
        if (readcount == 0)
            semSignal (wsem);
        semSignal (x);
    }
}
void writer ()
{
    while (true)
    {
        semWait (y);
        writecount++;
        if (writecount == 1)
            semWait (rsem);
        semSignal (y);
        semWait (wsem);
        WRITEUNIT ();
        semSignal (wsem);
        semWait (y);
        writecount--;
        if (writecount == 0)
            semSignal (rsem);
        semSignal (y);
    }
}
void main()
{
    readcount = writecount = 0;
    parbegin (reader, writer);
}

```

z: prevent long reader queue;
only 1 reader lines up at rsem,
other readers line up at z

y: controls updating of writecount

Figure 5.23 A Solution to the Readers/Writers Problem Using Semaphores: Writers Have Priority