

# Concurrency: Mutual Exclusion and Synchronization

## Chapter 5

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## Concurrency

- Multiple applications
- Structured applications
- Operating system structure

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# Concurrency

Table 5.1 Some Key Terms Related to Concurrency

<b>critical section</b>	A section of code within a process that requires access to shared resources and which may not be executed while another process is in a corresponding section of code.
<b>deadlock</b>	A situation in which two or more processes are unable to proceed because each is waiting for one of the others to do something.
<b>livelock</b>	A situation in which two or more processes continuously change their state in response to changes in the other process(es) without doing any useful work.
<b>mutual exclusion</b>	The requirement that when one process is in a critical section that accesses shared resources, no other process may be in a critical section that accesses any of those shared resources.
<b>race condition</b>	A situation in which multiple threads or processes read and write a shared data item and the final result depends on the relative timing of their execution.
<b>starvation</b>	A situation in which a runnable process is overlooked indefinitely by the scheduler; although it is able to proceed, it is never chosen.

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## Difficulties of Concurrency

- Sharing of global resources
- Operating system managing the allocation of resources optimally
- Difficult to locate programming errors

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## Currency

- Communication among processes
- Sharing resources
- Synchronization of multiple processes
- Allocation of processor time

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## Concurrency

- Multiple applications
  - Multiprogramming
- Structured application
  - Application can be a set of concurrent processes
- Operating-system structure
  - Operating system is a set of processes or threads

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## A Simple Example

```
void echo()  
{  
    chin = getchar();  
    chout = chin;  
    putchar(chout);  
}
```

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## A Simple Example

- Assume
  - single processor
  - 2 processes execute echo
  - global variables

```
void echo()  
{  
    chin = getchar();  
    chout = chin;  
    putchar(chout);  
}
```

- What are the possible outputs?

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## A Simple Example

Now assume 2 processors

**Process P1**

```
.  
chin = getchar();  
.   
chout = chin;  
putchar(chout);  
.   
.
```

**Process P2**

```
.   
.   
chin = getchar();  
chout = chin;  
.   
putchar(chout);  
.   
.
```

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## Operating System Concerns

- Keep track of various processes
- Allocate and deallocate resources
  - Processor time
  - Memory
  - Files
  - I/O devices
- Protect data and resources
- Output of process must be independent of the speed of execution of other concurrent processes

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# Process Interaction

- Processes unaware of each other
- Processes indirectly aware of each other
- Process directly aware of each other

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Table 5.2 Process Interaction

Degree of Awareness	Relationship	Influence that one Process has on the Other	Potential Control Problems
Processes unaware of each other	Competition	<ul style="list-style-type: none"> <li>•Results of one process independent of the action of others</li> <li>•Timing of process may be affected</li> </ul>	<ul style="list-style-type: none"> <li>•Mutual exclusion</li> <li>•Deadlock (renewable resource)</li> <li>•Starvation</li> </ul>
Processes indirectly aware of each other (e.g., shared object)	Cooperation by sharing	<ul style="list-style-type: none"> <li>•Results of one process may depend on information obtained from others</li> <li>•Timing of process may be affected</li> </ul>	<ul style="list-style-type: none"> <li>•Mutual exclusion</li> <li>•Deadlock (renewable resource)</li> <li>•Starvation</li> <li>•Data coherence</li> </ul>
Processes directly aware of each other (have communication primitives available to them)	Cooperation by communication	<ul style="list-style-type: none"> <li>•Results of one process may depend on information obtained from others</li> <li>•Timing of process may be affected</li> </ul>	<ul style="list-style-type: none"> <li>•Deadlock (consumable resource)</li> <li>•Starvation</li> </ul>

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## Competition Among Processes for Resources

- Mutual Exclusion
  - Critical sections
    - Only one program at a time is allowed in its critical section
    - Example only one process at a time is allowed to send command to the printer
- Deadlock
- Starvation

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## Requirements for Mutual Exclusion

- Only one process at a time is allowed in the critical section for a resource
- A process that halts in its non-critical section must do so without interfering with other processes
- No deadlock or starvation

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## Requirements for Mutual Exclusion cont.

- A process must not be delayed access to a critical section when there is no other process using it
- No assumptions are made about relative process speeds or number of processes
- A process remains inside its critical section for a finite time only

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## Mutual Exclusion: Hardware Support

- Interrupt Disabling
  - In general: A process runs until it invokes an operating system service or until it is interrupted
  - Uni-processor: Disabling interrupts guarantees mutual exclusion
    - Processor is limited in its ability to interleave programs
  - Multiprocessing
    - disabling interrupts on one processor will not guarantee mutual exclusion

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## Mutual Exclusion: Hardware Support

- Special Machine Instructions
  - Performed in a single instruction cycle
  - Access to the memory location is blocked for any other instructions

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## Mutual Exclusion: Hardware Support

- Test and Set Instruction

```
boolean testset (int i) {
    if (i == 0) {
        i = 1;
        return true;
    }
    else {
        return false;
    }
}
```

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## Mutual Exclusion: Hardware Support

- Exchange Instruction

```
void exchange(int register,
              int memory) {
    int temp;
    temp = memory;
    memory = register;
    register = temp;
}
```

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## Mutual Exclusion

- parbegin: initiate all processes and resume program after all  $P_i$ 's have terminated

```
/* program mutualexclusion */
const int n = /* number of processes */;
int bolt;
void P(int i)
{
    while (true)
    {
        while (!testset (bolt))
            /* do nothing */;
        /* critical section */;
        bolt = 0;
        /* remainder */
    }
}
void main()
{
    bolt = 0;
    parbegin (P(1), P(2), . . . ,P(n));
}
```

(a) Test and set instruction

```
/* program mutualexclusion */
int const n = /* number of processes*/;
int bolt;
void P(int i)
{
    int keyi;
    while (true)
    {
        keyi = 1;
        while (keyi != 0)
            exchange (keyi, bolt);
        /* critical section */;
        exchange (keyi, bolt);
        /* remainder */
    }
}
void main()
{
    bolt = 0;
    parbegin (P(1), P(2), . . . , P(n));
}
```

(b) Exchange instruction

Figure 5.2 Hardware Support for Mutual Exclusion

## Mutual Exclusion Machine Instructions

- Advantages
  - Applicable to any number of processes on either a single processor or multiple processors sharing main memory
  - It is simple and therefore easy to verify
  - It can be used to support multiple critical sections

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## Mutual Exclusion Machine Instructions

- Disadvantages
  - Busy-waiting consumes processor time
  - Starvation is possible when a process leaves a critical section and more than one process is waiting.
  - Deadlock
    - If a low priority process has the critical section and a higher priority process needs it, the higher priority process will obtain the processor to wait for the critical section (which will not be returned).

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