

Theft-Induced Checkpointing for Reconfigurable Dataflow Applications

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This work has been supported by the Region Rhône-Alpes (Ragtime project)
the CNRS ACI Grid-DOCG and Damascus University

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Presentation Outline

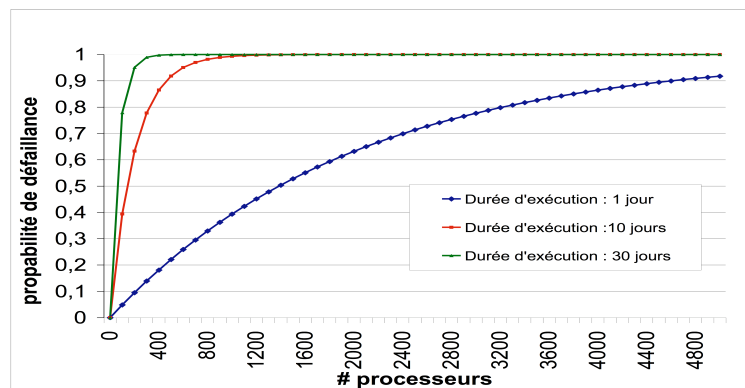
- ◆ **Motivation and background**
- ◆ Execution model
- ◆ Theft-induced checkpointing
- ◆ Experimental results
- ◆ Conclusions and Future Work

Target Application

- ◆ Large-Scale Global Computing Systems
 - (potentially) large number of nodes
 - volatility of nodes, e.g. dynamic run-time behavior
 - heterogeneous computing environment
- ◆ Dependability Problems
 - reliability issues of large number of nodes
 - without fault-tolerance mechanism application may be infeasible
 - » MTBF may sink below application execution time

Unreliability in the absence of FT

- ◆ Computation on Cluster
 - MTBF = 2000 days (48,000h, approx. 5 1/2 years)
 - Unreliability of one node: $F(t) = 1 - R(t) = 1 - e^{-\lambda t}$



Fault-tolerance Approaches

- ◆ Redundancy
 - Duplication

 - Checkpointing
 - » uncoordinated
 - » coordinated
 - » communication-induced

 - Message-logging
 - » optimistic
 - » pessimistic
 - » causal

Comparing Protocols

- ◆ Coordination
 - processes coordinate to build consistent global state at time of checkpointing or recovery

- ◆ Heterogeneity
 - checkpoint state can be restored on variety of platforms

- ◆ Scope of recovery
 - local or global recovery
 - local recovery: only roll-back of crashed process is necessary

Roll-back Methods

- ◆ Log-based
 - relies on logging and replaying of messages
 - process can be modeled as sequence of interval states, each one representing a non-deterministic event [Strom & Yemini 1985]

- ◆ Checkpoint-based
 - periodically save global state of computation to stable storage [Chandy & Lamport 1985]
 - differ in the way processes are coordinated
 - and on the interpretation of a consistent global state

Checkpointing

- ◆ Coordinated checkpointing
 - coordination of all processes for building consistent state before writing checkpoint to safe storage
 - » e.g. [Ftc-Charm++, CoCheck]

- ◆ Uncoordinated checkpointing
 - each process independently saves state
 - consistent global state is achieved in recovery phase
 - possibility of domino effect

- ◆ Communication induced checkpointing
 - compromise between coordinated and uncoordinated
 - consistent global state achieved by forcing additional checkpoints based on some information piggy bagged on application message [Baldone 1997]

Motivating Conclusion

- ◆ Lack of solutions for
 - large parallel applications
 - dynamic execution environment
 - heterogeneous processing environment
 - » potentially SMP
- ◆ Portability
 - achieved by portable languages, e.g. Java
 - or compilation into application code, e.g. Porch
 - but not on the checkpointing method itself

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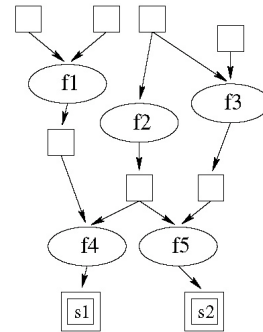
Definitions and Assumptions

- ◆ Application represented by Dataflow Graph

- $G = (\mathcal{V}, \mathcal{E})$

- \mathcal{V} finite set of vertices v_i

- \mathcal{E} set of edges e_{jk} vertices $v_j, v_k \in \mathcal{V}$



- ◆ Two kinds of tasks

- T_i Tasks
in the traditional sense

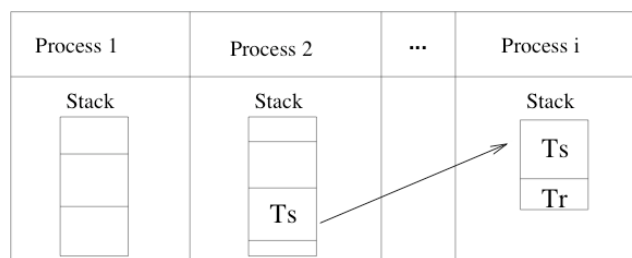
- D_j Data tasks
inputs and outputs

KAAPI Execution Model

- ◆ Kernel for Adaptive, Asynchronous Parallel Interface

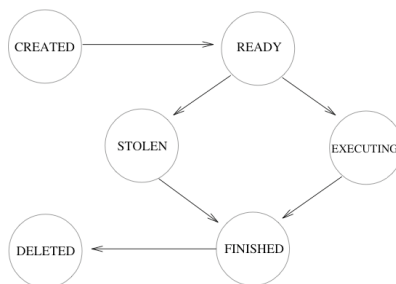
- implemented as C++ library
 - schedule programs at fine or medium granularity in distr. environment
 - KAAPI reference: <http://moais.imag.fr/>

- ◆ Relationship between processors and processes



Live-cycle of a Task in KAAPI

- ◆ **Work-Stealing**
 - primary method of scheduling workload
 - represents only communication between processes
- ◆ **The states of a task**
 - from a local process' point of view
 - in the context of work-stealing



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Theft-Induced Checkpointing

- ◆ State of the execution
 - based on macro dataflow graph
 - » dynamic: changes during execution
 - » portable: graph or portions of graph may be moved during execution
- ◆ Definition
 - *The macro dataflow graph G describes a platform-independent, and thus portable, consistent global state of the execution of an application.*

Theft-Induced Checkpointing

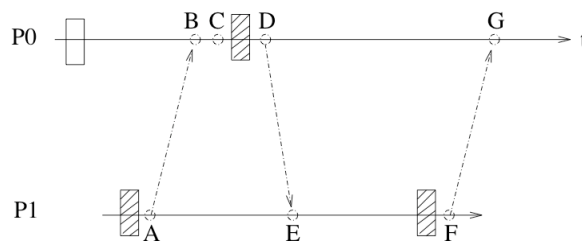
- ◆ Definition of a checkpoint
 - Checkpoints are with respect to a process P_i
 - The checkpoint of P_i consists of the entries of G_i , the process stack
 - » i.e. its tasks and their associated inputsand **not of the task execution state** on the processor itself
- ◆ Important difference:
 - one simply checkpoints the tasks and their inputs
 - => platform independent
 - one does NOT checkpoint the task's execution state
 - => process context is platform dependent
 - Note: the content of a checkpoint G_i is only the dataflow graph representing the "future of the computation".

Two Types of Checkpoints

- ◆ Local Checkpoint
 - each process takes a “local” checkpoint
 - » at the expiration of a checkpointing interval τ
 - after completion of the currently executing task
- ◆ Forced Checkpoint
 - needed to address global consistency in the presence of communication
 - a checkpoint is taken as the result of work-stealing
 - actions on thief and victim are defined by protocol
- ◆ Both concepts will be used in the checkpointing protocol presented

Theft-Induced Checkpointing (TIC)

- ◆ TIC Protocol
 - victim P0 has ready-task(s)
 - thief P1 is created on idle resource and initiates a theft operation
 - each theft results in exactly 3 checkpoints
 - » the checkpoints before events A and F contain only single task

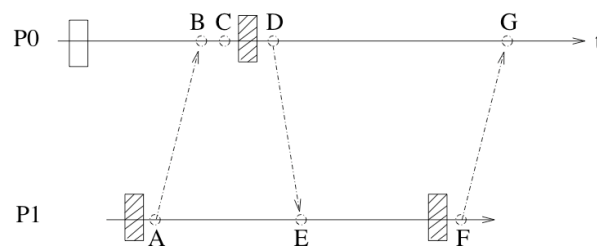


TIC rollback

- ◆ Strength of TIC: rollback of single crashed process
- ◆ Need to guarantee consistent global state of execution:
- ◆ Question 1:
What does a process do that needs to send a message to a crashed process?
 - attempted communication with crashed process results in error
 - manager identifies the replacement processor

TIC rollback

- ◆ Question2:
How can a process that is rolled back receive messages that it received after the last checkpoint and before the crash?
 - 1) loss of theft request (event A)
 - 2) crash of thief after event E but before able to checkpoint theft
 - 3) crash of victim after receiving result (event G) but before being able to checkpoint



Bound on TIC Rollback Loss

- ◆ What is the maximum computation time loss due to rollback?
 - T_I : execution time of “parallel” application on single processor
 - » note: not the same as execution time of sequential application execution
 - T_∞ : execution time on unlimited number of processors
 - p_i : processing time of task T_i

$$\text{Max loss} = \tau + \max(p_i)$$

- But how bad can this loss be?
 - » in parallel application one can always assume $T_\infty \ll T_I$
 - » and $p_i \leq T_\infty$

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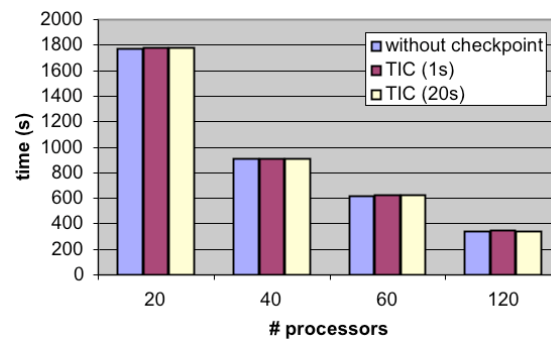
Experimental Results

- ◆ Application: DOCG
 - Combinatorial optimization, Branch & Bound algorithm
 - QAP: Quadratic Assignment Problem
 - Problem size: NUGENT 22
- ◆ Platform: iCluster2 at IMAG
 - 104 dual-processor Itanium2
 - 900 MHz
 - 100Base Ethernet



TIC Overhead

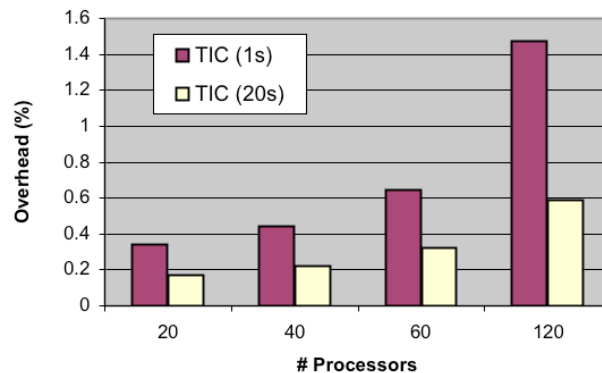
- ◆ Implemented using distributed checkpoint services
 - two checkpointing periods
 - max overhead observed: 1.5%



Relative TIC Overhead

◆ Differences observed

- overhead increases as the number of processors increases
 - » more forced checkpoints due to work-stealing



Conclusions

- ◆ Theft-Induced Checkpointing was introduced
- ◆ Requires only crashed processes to be rolled back
- ◆ State of application represented in portable fashion
 - macro dataflow graph
 - platform independent description of application state
- ◆ Roll-back possible in
 - dynamic environment
 - heterogeneous infrastructure
- ◆ Experimental results indicate low checkpointing overhead
- ◆ Max roll-back loss can be controlled
 - selection of suitable period, granularity of application

Questions?