

# Shortest Remaining Time (SRT)

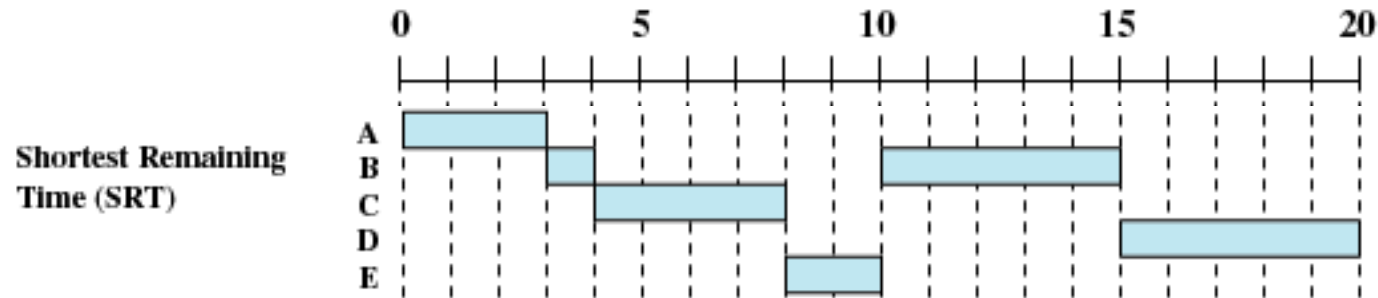


Table 9.4 Process Scheduling Example

Process	Arrival Time	Service Time
A	0	3
B	2	6
C	4	4
D	6	5
E	8	2

- Preemptive version of shortest process next policy
- Must estimate processing time

# Response Time and Ratio

- Response Ratio  $R$  is
  - total time spent waiting and executing normalized to the execution time
  - $w$ : waiting time (waiting for a processor)
  - $s$ : expected service (execution) time

$$R = \frac{w + s}{s}$$

- Note: In scheduling theory response time is called **flow time**  $F_i = C_i - r_i$ 
  - i.e., completion time minus ready time
  - this is the sum of waiting and processing times

# Highest Response Ratio Next (HRRN)

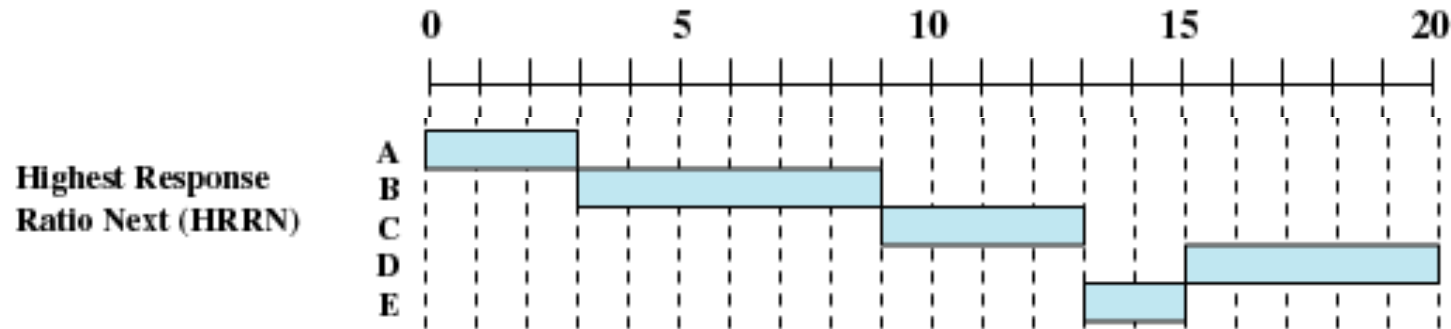


Table 9.4 Process Scheduling Example

Process	Arrival Time	Service Time
A	0	3
B	2	6
C	4	4
D	6	5
E	8	2

- Choose next process with the greatest response ratio

# Feedback

- SPN, SRT and HRRN require that something is known about the execution times
  - e.g., expected execution time
- Alternative policies
  - give preference to shorter tasks by penalizing tasks that have been running longer

Use multiple queues, pushing tasks to the next queue after each preemption

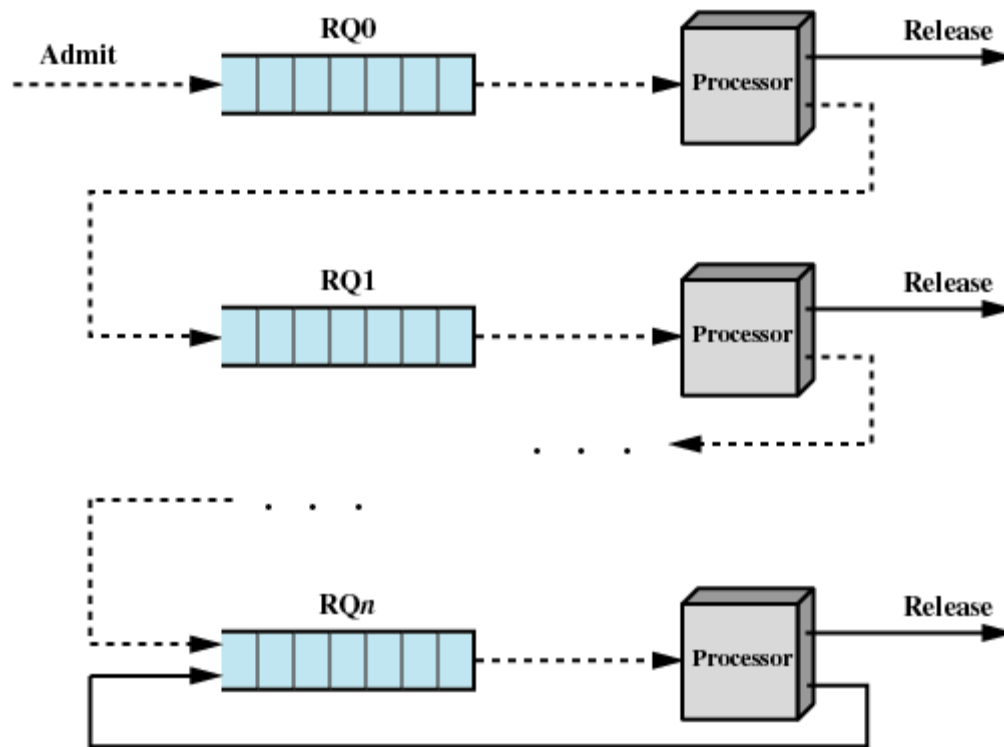
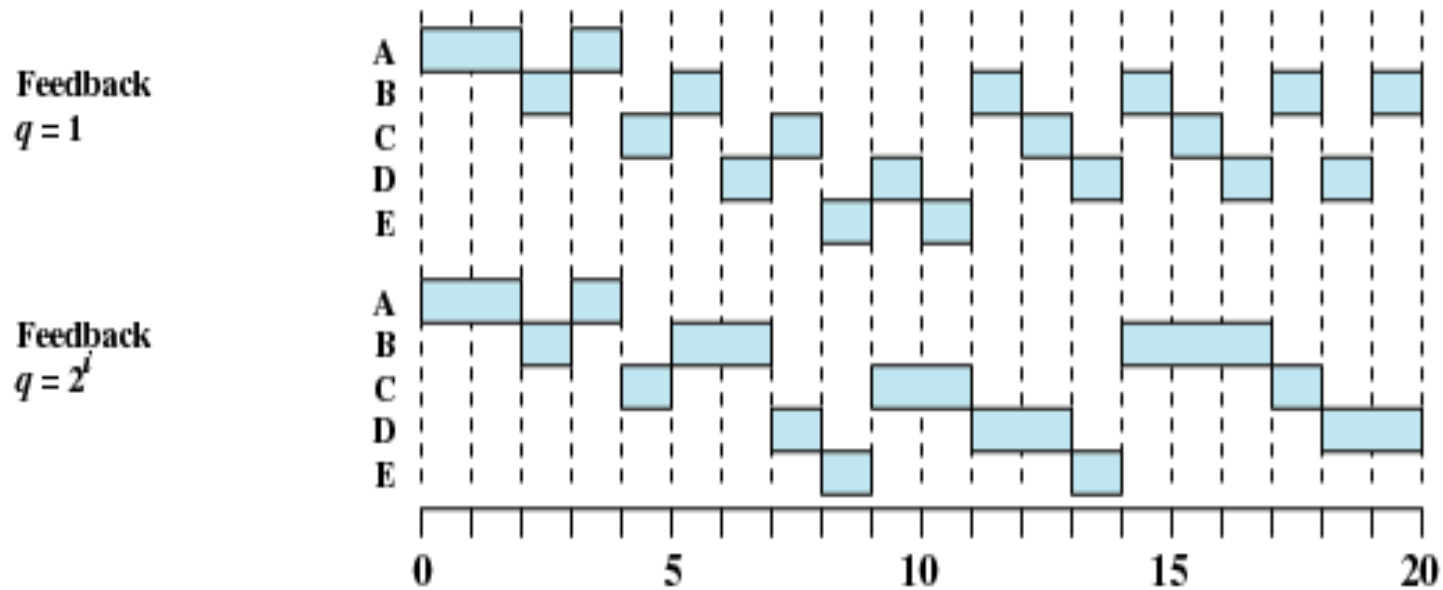


Figure 9.10 Feedback Scheduling

# Feedback

- Potential problems
  - starvation
  - low response times for longer tasks
  - many solutions exists, e.g.,
    - use fixed quantum
      - $q = 1$
    - use different quantum in consequent queues
      - $q = 2^i$  for queue  $i$
      - starvation still possible though
        - » solution: “promote” jobs to higher queue after some time

# Feedback



- Don't know remaining time process needs to execute

Table 9.4 Process Scheduling Example

Process	Arrival Time	Service Time
A	0	3
B	2	6
C	4	4
D	6	5
E	8	2

**Table 9.3 Characteristics of Various Scheduling Policies**

	<b>Selection Function</b>	<b>Decision Mode</b>	<b>Throughput</b>	<b>Response Time</b>	<b>Overhead</b>	<b>Effect on Processes</b>	<b>Starvation</b>
<b>FCFS</b>	$\max[w]$	Nonpreemptive	Not emphasized	May be high, especially if there is a large variance in process execution times	Minimum	Penalizes short processes; penalizes I/O bound processes	No
<b>Round Robin</b>	constant	Preemptive (at time quantum)	May be low if quantum is too small	Provides good response time for short processes	Minimum	Fair treatment	No
<b>SPN</b>	$\min[s]$	Nonpreemptive	High	Provides good response time for short processes	Can be high	Penalizes long processes	Possible
<b>SRT</b>	$\min[s - e]$	Preemptive (at arrival)	High	Provides good response time	Can be high	Penalizes long processes	Possible
<b>HRRN</b>	$\max\left(\frac{w + s}{s}\right)$	Nonpreemptive	High	Provides good response time	Can be high	Good balance	No
<b>Feedback</b>	(see text)	Preemptive (at time quantum)	Not emphasized	Not emphasized	Can be high	May favor I/O bound processes	Possible

$w$  = time spent waiting

$e$  = time spent in execution so far

$s$  = total service time required by the process, including  $e$



**Table 9.5 A Comparison of Scheduling Policies**

	Process	A	B	C	D	E	
	Arrival Time	0	2	4	6	8	
	Service Time ( $T_s$ )	3	6	4	5	2	Mean
FCFS	Finish Time	3	9	13	18	20	
	Turnaround Time ( $T_r$ )	3	7	9	12	12	8.60
	$T_r/T_s$	1.00	1.17	2.25	2.40	6.00	2.56
RR $q = 1$	Finish Time	4	18	17	20	15	
	Turnaround Time ( $T_r$ )	4	16	13	14	7	10.80
	$T_r/T_s$	1.33	2.67	3.25	2.80	3.50	2.71
RR $q = 4$	Finish Time	3	17	11	20	19	
	Turnaround Time ( $T_r$ )	3	15	7	14	11	10.00
	$T_r/T_s$	1.00	2.5	1.75	2.80	5.50	2.71
SPN	Finish Time	3	9	15	20	11	
	Turnaround Time ( $T_r$ )	3	7	11	14	3	7.60
	$T_r/T_s$	1.00	1.17	2.75	2.80	1.50	1.84
SRT	Finish Time	3	15	8	20	10	
	Turnaround Time ( $T_r$ )	3	13	4	14	2	7.20
	$T_r/T_s$	1.00	2.17	1.00	2.80	1.00	1.59
HRRN	Finish Time	3	9	13	20	15	
	Turnaround Time ( $T_r$ )	3	7	9	14	7	8.00
	$T_r/T_s$	1.00	1.17	2.25	2.80	3.5	2.14
FB $q = 1$	Finish Time	4	20	16	19	11	
	Turnaround Time ( $T_r$ )	4	18	12	13	3	10.00
	$T_r/T_s$	1.33	3.00	3.00	2.60	1.5	2.29
FB $q = 2^i$	Finish Time	4	17	18	20	14	
	Turnaround Time ( $T_r$ )	4	15	14	14	6	10.60
	$T_r/T_s$	1.33	2.50	3.50	2.80	3.00	2.63

**Table 9.6 Formulas for Single-Server Queues with Two Priority Categories**

- Assumptions:
1. Poisson arrival rate.
  2. Priority 1 items are serviced before priority 2 items.
  3. First-in-first-out dispatching for items of equal priority.
  4. No item is interrupted while being served.
  5. No items leave the queue (lost calls delayed).

**(a) General Formulas**

$$\lambda = \lambda_1 + \lambda_2 \quad \text{arrival rate}$$

$$\rho_1 = \lambda_1 T_{s1}; \quad \rho_2 = \lambda_2 T_{s2} \quad \text{utilization}$$

$$\rho = \rho_1 + \rho_2$$

$$T_s = \frac{\lambda_1}{\lambda} T_{s1} + \frac{\lambda_2}{\lambda} T_{s2} \quad \text{average service time}$$

$$T_r = \frac{\lambda_1}{\lambda} T_{r1} + \frac{\lambda_2}{\lambda} T_{r2} \quad \text{turnaround time}$$

**b) No interrupts; exponential service times**

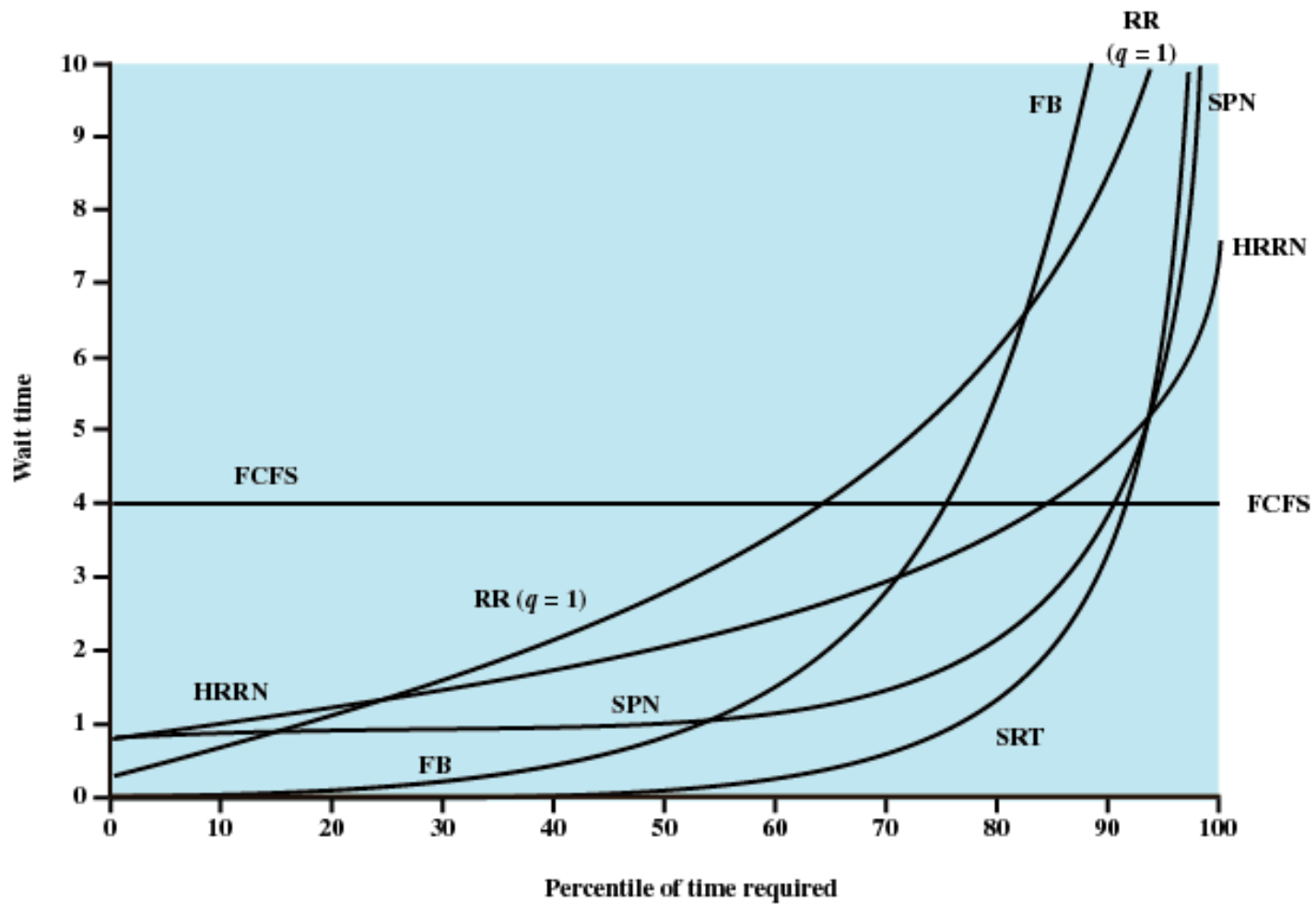
$$T_{r1} = T_{s1} + \frac{\rho_1 T_{s1} + \rho_2 T_{s2}}{1 - \rho_1}$$

$$T_{r2} = T_{s2} + \frac{T_{r1} - T_{s1}}{1 - \rho}$$

**(c) Preemptive-resume queuing discipline; exponential service times**

$$T_{r1} = T_{s1} + \frac{\rho_1 T_{s1}}{1 - \rho_1}$$

$$T_{r2} = T_{s2} + \frac{1}{1 - \rho_1} \left( \rho_1 T_{s2} + \frac{\rho T_s}{1 - \rho} \right)$$



**Figure 9.15 Simulation Results for Waiting Time**

# Fair-Share Scheduling

- All previous approaches treat collection of ready processes as single pool
- User's application runs as a collection of processes (threads)
  - concern about the performance of the application, not single process; (this changes the game)
  - need to make scheduling decisions based on process sets

# Fair-Share Scheduling

- Philosophy can be extended to groups
  - e.g. time-sharing system,
    - all users from one department treated as group
    - the performance of that group should not affect other groups significantly
      - e.g. as many people from the group log in performance degradation should be primarily felt in that group

# Fair-Share Scheduling

- Fair share
  - each user is assigned a weight that corresponds to the fraction of total use of the resources
  - scheme should operate approximately linear
    - e.g. if user A has twice the weight of user B, then (in the long run), user A should do twice the work than B.

# Traditional UNIX Scheduling

- Multilevel feedback using round robin within each of the priority queues
- If a running process does not block or complete within 1 second, it is preempted
- Priorities are recomputed once per second
- Base priority divides all processes into fixed *bands* of priority levels

# Bands

- Decreasing order of priority
  - Swapper
  - Block I/O device control
  - File manipulation
  - Character I/O device control
  - User processes